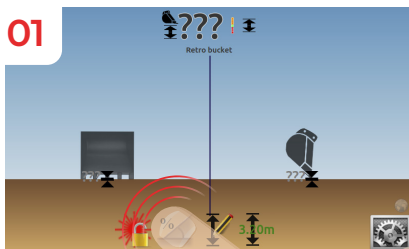
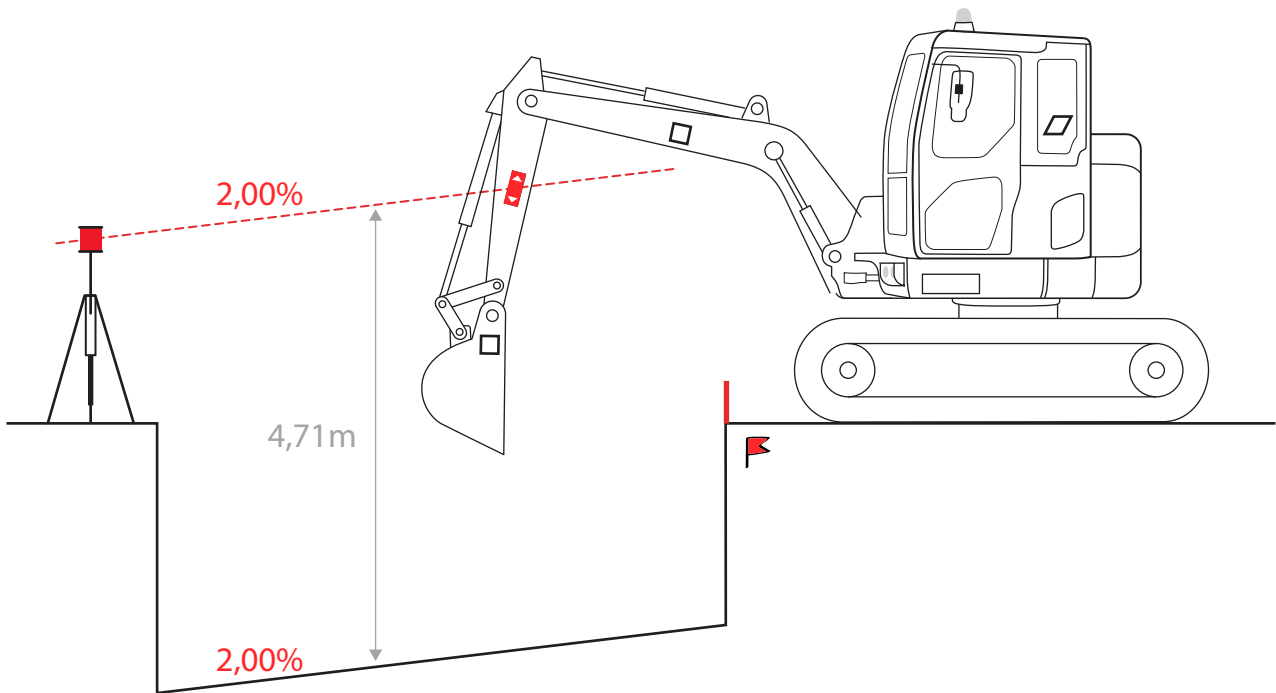
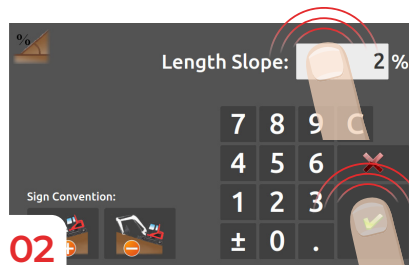


# DIGGING A TRENCH WITH A 2% SLOPE USING A ROTARY LASER

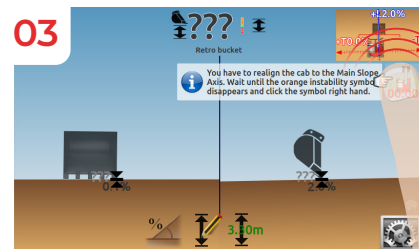
Method 1: knowing the height of the laser relative to a point.



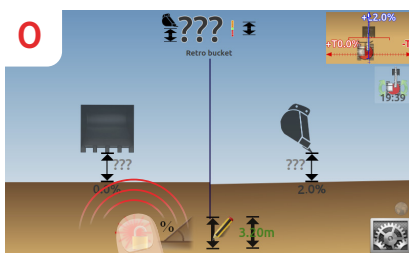
01 Activate Slope mode.



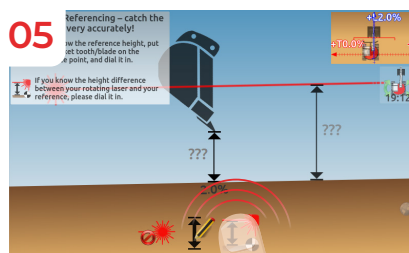
02 Enter 2%, then confirm.



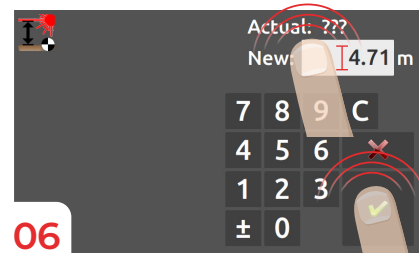
03 Align your boom with the trench.



04 Activate Laser mode.



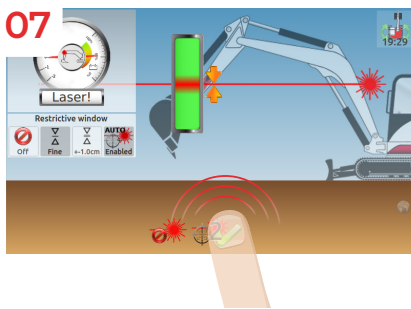
05 Click on « Define laser height ».



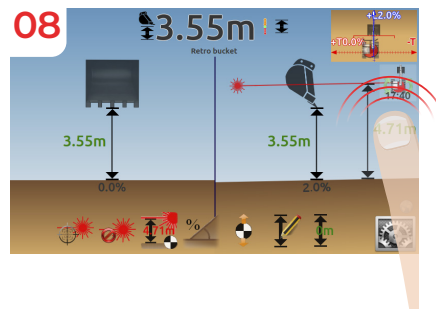
06 Enter "4.71m" and confirm.

# DIGGING A TRENCH WITH A 2% SLOPE USING A ROTARY LASER

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Catch the laser beam.

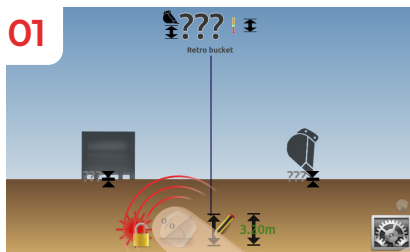
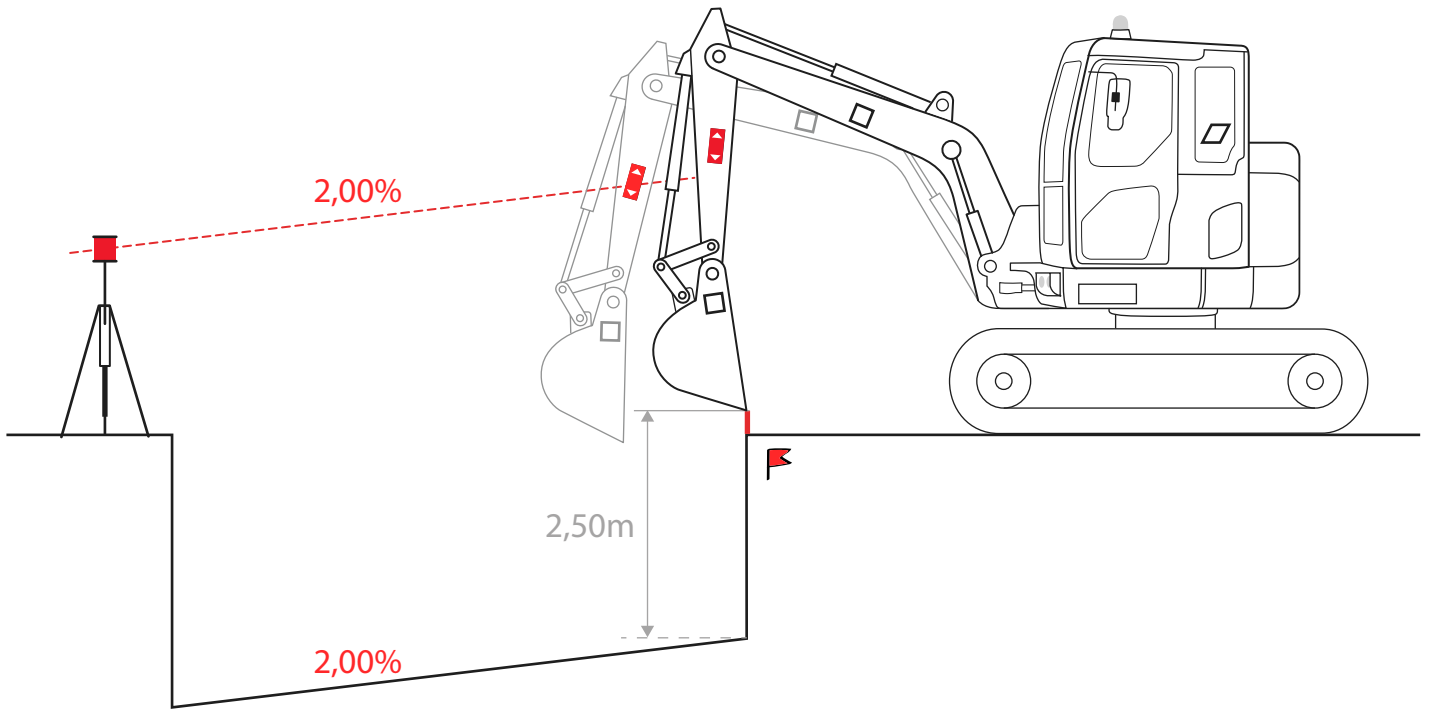


The entered laser height (4.71m) is displayed, and in this example, the calculation shows that the bucket is “**3.55m**” from the bottom of the trench.

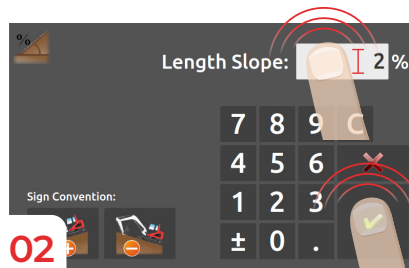
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# DIGGING A TRENCH WITH A 2% SLOPE USING A ROTARY LASER

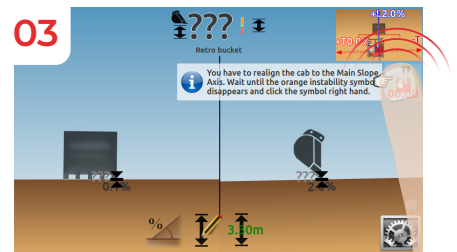
Method 2: without knowing the height of the laser.



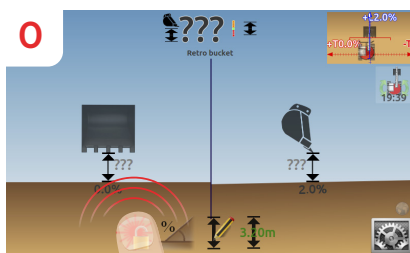
Activate Slope mode.



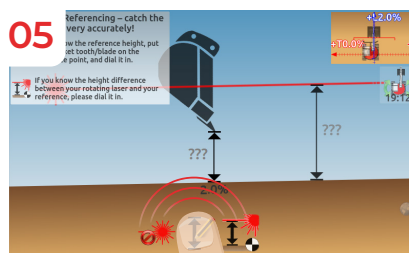
Enter 2%, then confirm.



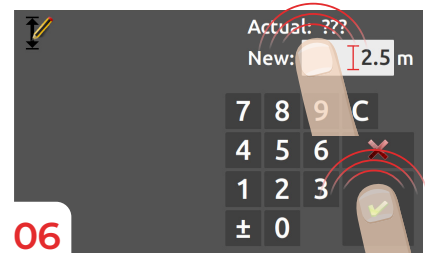
Align your boom with the trench.



Activate laser mode.



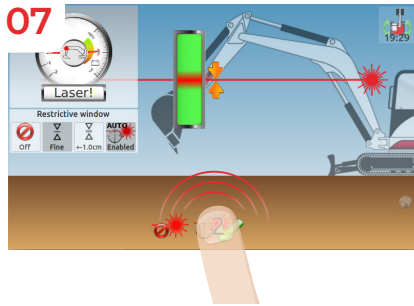
Click on « depth ».



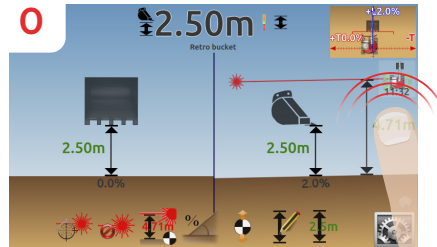
Place the bucket tip on the benchmark, then enter "2.5m" and confirm.

# DIGGING A TRENCH WITH A 2% SLOPE USING A ROTARY LASER

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Catch the laser.



In this example, the calculation shows that the laser is "4.71m" from the bottom of the trench, and the bucket is "2.50m" from the bottom.

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